

# 2023 Rules For POWERPLAY<sup>SM</sup>

The following rules are in addition or modification to the most recent version of the *FIRST* Tech Challenge 2023 Game, POWERPLAY<sup>SM</sup> presented by Raytheon Technologies, and its listed Game Manuals 1 and 2 for traditional events. Refer back to Game Manuals 1 and 2, and the Field Assembly and Setup Guide for rules and details not explicitly listed here.

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Revisi	on History	Date
1.0	Initial Release	March 27, 2023
1.1	<ul> <li>Clarified Transformer scoring requirements (pg 6)</li> <li>Updated Round Robin Schedule (Diagram 5, pg 13)</li> <li>Updated GS7 to account for Transformer actions being nullified (pg 16)</li> <li>Clarified Scoring Summary (pg 17)</li> </ul>	April 12, 2023

Updated text will be **bold blue** text to indicate change from the previous revision of the manual.



# Chicago Robotics Invitational 2023 Field

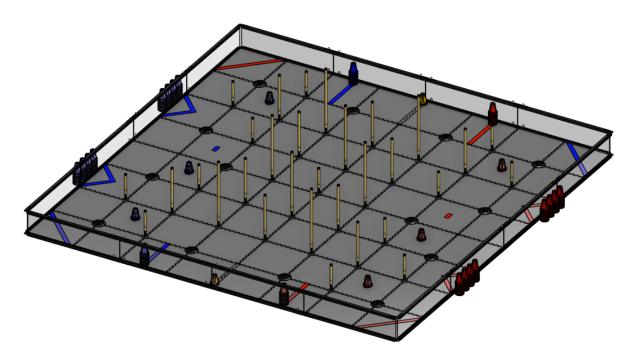


Diagram 1: Field Overview (Onshape CAD Link)

# Field and Scoring Achievement Changes

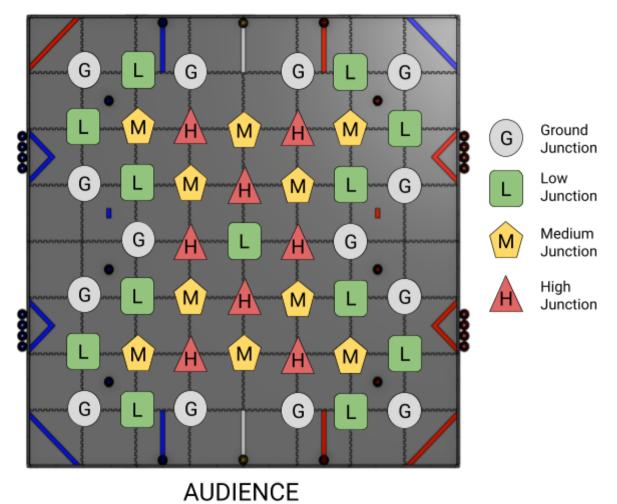
The *Field* has been added to in both length and width to be a larger square *Field*. This means that an extra *Field Wall* segment is placed on each side, with two (2) rows of gray *Tiles* accordingly added. The field is now approximately 8 *Tiles* wide by 8 *Tiles* long, for total dimensions of approximately 16' x 16'.

An Alliance for CRI is made up of three (3) Teams on the Field. During Elimination Matches, an Alliance may be made up of four (4) Teams, but only three (3) of that Alliance's Teams are on the Field for any given Match.



#### **Junctions**

With the expanded *Field*, the arrangement of the various *Junctions* on the Field has been altered. The *Ground*, *Low*, *Medium* and *High Junctions* are all still of the same design and height, but arranged in the order depicted below. This pattern is symmetric over the centerlines of the *Field*, but it is intentionally not diagonally symmetric.



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Diagram 2: Junction Locations



#### Substations

With the addition of two (2) more *Teams* on the *Field*, each *Alliance* has another *Substation* to use during gameplay. The *Substations* are now resized and moved to fit entirely within a *Field Tile*. The *Red Alliance's Substations* are located entirely within *Tiles* H3 and H6, while the *Blue Alliance's Substations* are located entirely within *Tiles* A3 and A6. See the <u>Tile Locations Appendix</u> for the descriptions of these locations. Also note the updated definition of *Drive Team* for the *Human Players* per *Alliance*.

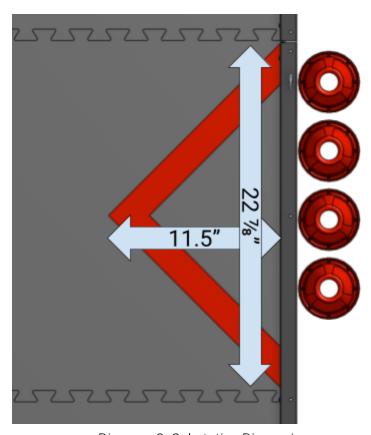


Diagram 3: Substation Dimensions

#### **Transformers**

An additional *Scoring Element* has been introduced to the game, which is the same shape and dimension as a cone (but is not a *Cone*). *Transformers* are constructed from a Red or Blue *Cone* but are spray painted yellow using <u>Rust-Oleum Painter's Touch Ultra Cover 2X Gloss Sun Yellow General Purpose Spray Paint</u>.

The Field contains two (2) extra tape lines, similar to the Cone Stack tape lines, on the midline of the Field located directly next to the audience facing wall and far wall of the Field. One (1) line is centered between the D1/E1 pair of Tiles, and the other line is centered between the D8/E8 pair of



*Tiles*. Before the start of the match, one (1) *Transformer* will be placed centered on each tape line, touching the *Field Wall*, for a total of two (2) *Transformers* starting on the *Field*.

All Scoring Achievements are Scored at Rest.

Autonomous and Driver Controlled Points:

- Each Cone below a Secured Transformer will earn an additional three (3) Points for that Cone's corresponding Alliance. The Junction with a Secured Transformer is considered Owned by both Alliances for purposes of completing a Circuit, but both Alliances earn zero (0) Points for Ownership.
- Any Cone or Beacon placed on top of a Secured Transformer will earn zero (0) Points and does not **convey** Ownership.
- A Transformer placed on top of a Secured Beacon has zero (0) Score value, does not impact the Score of the Cones below it, and does not convey Ownership.
- A Transformer in a Terminal has zero (0) Score value and does not convey Ownership.

Transformers that are Scored in the Autonomous Period will earn points for the Cones under the Transformers at the end of the Autonomous Period in addition to Points at the end of the Driver-Controlled Period if they remain in place, similar to the scoring of Cones.

For example, if a *High Junction* contains three (3) *Red Cones* and four (4) *Blue Cones* and a *Transformer* is *Secured* on top of those *Cones*, this would generate an additional 9 *Points* for the *Red Alliance* and 12 points for the *Blue Alliance.*, no matter which *Alliance Secures* the *Transformer* on the *Junction*. Red would have a total of 15+9=26 points for this *Junction* and Blue will have a total of 20+12=32 points for this Junction. *Ownership* will earn 0 points, but *Ownership* will be shared by both *Alliances*.

## Field Set-Up Changes

There are now four (4) potential starting *Tiles* for each *Alliance*, of which, three (3) positions must be used as described below, provided three (3) *Teams* are present for the *Match*.

- 1. For the Blue *Alliance*:
  - a. One (1) Robot must start Completely In Tile A2
  - b. One (1) Robot must start Completely In Tile A7
  - c. One (1) Robot must start Completely In either Tile A4 or A5.
- 2. For the Red *Alliance*:
  - a. One (1) Robot must start Completely In Tile F2
  - b. One (1) Robot must start Completely In Tile F7
  - c. One (1) Robot must start Completely In either Tile F4 or F5.

See the <u>Tile Locations Appendix</u> for the descriptions of these locations.

The middle starting position options have two (2) taped *Signal Marks* for the starting position of a *Signal*. The *Signal* will start in the front-most position on *Tile* B4/G4 and teams may place their *Signal Sleeve* on it just like any other *Signal*. Teams may request that a *Referee* move this *Signal* to

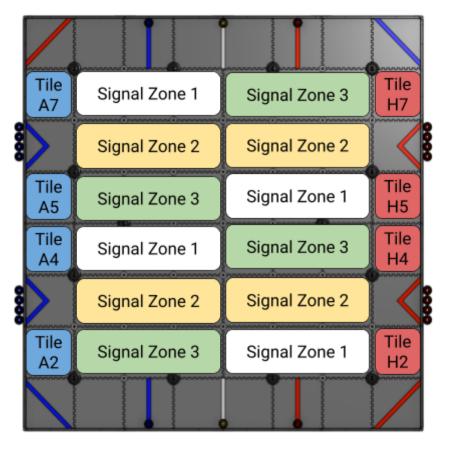


tile B5/G5, but may not move it themselves, just as they may not move or adjust the *Signals* on other *Signal Marks*.

Every Substation has a corresponding Substation Storage Area that has twenty (20) Cones arranged in the same four (4) stacks of five (5), as in the original game. This results in fifty (50) total Cones per Alliance on the Field: two (2) off-field Substation Storage Areas of 20, and two (2) on-field Cone stacks of five (5).

## Signal Zones

There are still two (2) sets of *Signal Zones* for each *Alliance*. Each of these *Signal Zones* are three (3) *Tiles* deep now but still one (1) *Tile* wide. See the below diagram for the exact positions.



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Diagram 4: Location of Signal Zones

NOTE: More than one (1) Robot can be Parked in each Signal Zone.



#### Circuit Points

Completing a Circuit is now worth forty (40) points.

## **Navigation Points**

A Robot Parked In either of their Alliance's Terminals during End Game now earns five (5) points.

## **Navigation Images**

There will be no Navigation Images on the Field Walls.

#### **Alliance Stations**

Alliance Stations will be 15 foot x 4.5 foot, in line with the longer Field. 6 inches of extra space is left on both the front and back of the Field to accommodate Field Personnel. The Alliance Station is also made a foot deeper to facilitate movement within the Alliance Station.



### **Definitions**

Changes to already existing rules and points are highlighted. New definitions, rules, or sub bullet points may just have the definition name, rule number of bullet point highlighted.

**Alliance** - An Alliance for CRI is made up of three (3) Teams on the Field, competing to earn the highest Score. During Elimination Matches, an Alliance may be made up of four (4) Teams, but only three (3) of that Alliance's Teams are on the Field for any given Match.

**Backup Team** - A Team who can be chosen to be a fourth (4th) member of an *Eliminations* Alliance in case of Robot failure.

**Drive Team** – Up to four (4) representatives; two (2) *Drivers*, one (1) *Human Player* and one (1) *Coach* from the same *Team*. Only two (2) *Human Players* will represent an entire *Alliance* in a *Match*.

**Finals** - The second and last Round of the Elimination Matches.

**Game Element** – Any item *Robots* interact with to play the game. *Game Elements* for this year's game include *Junctions, Cones, Transformers*, *Signals, Signal Sleeves*, and *Beacons*.

**Transformer** - A Scoring Element that is constructed from a Cone but is spray painted yellow. A Transformer is not a Cone. Two (2) Transformers start on the Field for a Match.

**Own / Owned** – An Alliance Owns a Junction when one of the following conditions is met:

- That Alliance has the topmost Scored Cone on that Junction, or
- That Alliance has a Scored Beacon on that Junction, or
- A Transformer is Secured on that Junction

A Terminal is Owned when it has at least one (1) Scored Cone.

**Round** - A subdivision of the *Elimination Matches* which will eliminate certain *Elimination Alliances*. For the purposes of CRI 2023, there are two (2) *Rounds*: the *Round Robin*, and the *Finals*.

**Round Robin** - The first Round of the Elimination Matches wherein each Eliminations Alliance plays each other Eliminations Alliance exactly once. Each Eliminations Alliance is ranked by Ranking Points and Tiebreaker Points from the Round Robin Matches, and the two (2) highest ranked Alliances advance onto the Finals.

**Scoring Elements** – Objects that *Robots* manipulate to earn points for their *Alliance*. The *Scoring Elements* are *Cones*, *Transformers*, and *Beacons*. A *Signal* is not a *Scoring Element*.



#### **Secured** - A Cone or Transformer is

- Secured in a Ground Junction when the 4-inch diameter base of the Cone or Transformer is Completely In the recess of the Junction or Completely On a Secured Cone.
- Secured in a Low, Medium or High Junction when the pole passes through the 1.25" diameter hole of the Cone or Transformer or it is Completely On a Secured Cone.

A Cone or Transformer is Secured only if the large opening is facing toward the Playing Field Floor.

**Series** - A subdivision of the *Round Robin* in which each *Elimination Alliance* plays exactly once.



#### **Tournament Rules**

#### Alliances & Ranking

Each Alliance for CRI 2023 is made up of three (3) Teams in each Qualifying Match. Competition Rankings from Qualifying Matches are calculated per Game Manual Part 1 - Traditional Events, Section 5 (also see definitions).

**<C29> Elimination Matches** - *Elimination Matches* differ from *Qualification Matches* in the following ways:

#### a. Alliance Size -

- i. Standard Alliance: Three (3) Team Alliances all Teams play in all Elimination Matches in which the Alliance competes.
- ii. Alliance with a Backup Robot: Four (4) Team Alliances. Three (3) of the Teams represent their Alliance in each Match as described below.
- b. Four (4) Team Alliances (The Alliance includes a Backup Team):
  - i. The Alliance Captain must let the referee know which three (3) Teams are playing in each Match, including calling a Backup Team. Failure to do this in a timely manner as described below results in a random draw to decide which Team(s) will compete in the Match. Teams should communicate this to the Head Referee at least four minutes (4:00) prior to the start of the Match.
  - ii. The *Team* that is not playing in a *Match* is allowed to have an extra *Drive Team* member in the *Alliance Station*. This additional representative may only serve as a *Coach*.
- c. **Match Timing** There are no *Team* requested timeouts. An *Alliance* has eight minutes (8:00) from the initial announcement or display of the *Match* results for their *Robots* to be set up on the playing field and ready for the start of their next *Match*. A *Match* may begin early if both *Alliances* are ready to begin a *Match* ahead of time.
- d. **Team Disqualification** If a *Team* is *Disqualified* during *Elimination Matches*, the entire *Alliance is Disqualified*.

#### Alliance Selection

Following *Qualifying Matches*, the *Alliance Selection* will occur to form six (6) *Alliances* of three (3) *Teams* each for the *Elimination Matches*. *Alliances* will be selected using a snake draft, in 1-6, 6-1 order. Typical *Alliance Selection* rules still apply.

Of the remaining eligible *Teams*, the highest ranked *Teams* must either accept or decline to be included in a pool of available *Backup Teams* until there are six (6) *Teams* that accept to be added into the *Backup* pool. *Field Staff* will coordinate the assembly of this *Backup* pool immediately after *Alliance Selection* has been finalized. If a *Team* is not available to accept inclusion in the *Backup* pool, it will be assumed they have declined the invitation.



Once a *Team* has accepted their invite into the *Backup* pool, there will be a designated place for *Backup Teams* to stay in the *Competition Area*. At least one (1) *Team* representative must stay in this area during the entirety of the *Elimination Matches*. The two (2) highest ranked *Teams* in the *Backup* pool also must have their *Robot, Driver Station* and any other materials needed for a *Team* to prepare their *Robot* for gameplay within three (3) minutes in this area. The other *Teams* in the *Backup* pool who are not the highest ranked *Teams* will be called to come to the *Competition Area* if these higher ranked *Teams* are called.

#### Backup Teams

In the *Elimination Matches*, it may be necessary for an *Alliance* to replace one (1) of its members due to a faulty *Robot*. In this situation, the *Alliance Captain* has the option to bring in only the highest seeded *Team* from the *Backup* pool to join its *Alliance*. The team whose *Robot* and *Drive Team* get added to an *Alliance* during the *Playoff Matches* is called the *Backup Team* for this *Alliance*.

The resulting *Alliance* is then composed of four (4) *Teams*. The *Backup Team* must be a part of the three (3) *Teams* who are playing for the next *Match* after the *Alliance* calls them. After the first *Match* that the *Backup Team* is playing is over, *Alliances* may play any three (3) of the four (4) *Teams* for any *Match*.

Each Alliance is allotted one (1) Backup Team coupon during the Elimination Matches. If a second Robot from the Alliance becomes inoperable, then the Alliance must play the following Matches with only two (2) (or even one (1)) Robots.

An *Alliance Captain* may choose to call up a *Backup Team* by submitting their *Backup Team* coupon to the *Head Referee* no later than when the *Alliance Captain* must notify the Referee which Teams are playing in the next match, as specified in <C29>. After that point, they will not be allowed to utilize the *Backup Team*.

The Head Referee will not accept the Backup Team coupon unless it lists the number of the Team whose Robot is being replaced and is initiated by the Alliance Captain. Once a Backup Team coupon is submitted and accepted by the Head Referee, the Backup Team coupon may not be withdrawn by the Alliance.

#### Flimination Matches

The *Elimination Matches* are when the *Alliances* compete to decide who the winning *Alliance* is. The *Matches* are played in the following *Rounds*:

#### Round Robin Round

Instead of standard Semi-Final Rounds, there will be a six (6) Alliance Round Robin. In this format, each Alliance plays one (1) Match against each of the other Alliances. This Round Robin format will be run in the following order:



Match	Series	Field	Red Alliance	Blue Alliance
1	1	1	1	2
2		2	4	3
3		1	5	6
4	2	2	3	2
5		1	6	4
6		2	5	1
7	3	1	4	2
8		2	6	1
9		1	5	3
10	4	2	2	6
11		1	3	1
12		2	4	5
13	5	1	6	3
14		2	1	4
15		1	2	5

Diagram 5: Round Robin Schedule

Each Alliance participating in the Round Robin Round will earn Ranking Points and Tiebreaker Points just like in Qualification Matches. Each Alliance participating in the Round Robin will be ranked based off of the following criteria:

Order	Criteria
1	Total Ranking Points (high to low)
2	Total TieBreaker Points (TBP1) (high to low)
3	Total TieBreaker Points (TBP2) (high to low)

Based on this *Round Robin Ranking* after all of the *Round Robin* matches are completed, the top two (2) ranked *Alliances* will advance to the *Finals Round*.



#### Finals Round

The highest ranked *Alliance* from the *Round Robin Ranking* will be the *Red Alliance* in the *Finals Matches*. The second highest ranked *Alliance* from the *Round Robin Ranking* will be the *Blue Alliance* in the *Finals Matches*.

Finals Matches are played to decide which Alliance wins the event. The event winning Alliance is the first Alliance to win two (2) Matches. Any tied Matches are replayed until one (1) Alliance has two (2) wins.



## Gameplay Rules

Unmodified bullet points under some of the following rules have been omitted from this Game Manual for the sake of brevity, but still apply.

#### <G12> Playing Field Access

c) Violations of this rule outside of normal *Match* play that are not sanctioned by the event will result in a *Yellow Card*, including scheduled practice times and *Robot* calibration.

**<G13> Pre-Match Robot Placement** – At the beginning of a *Match*, each *Alliance Robot* must be set up on the *Playing Field* according to section 4.5.1 *Pre-Match*. After *Robots* are set up on the *Playing Field*, *Drive Teams* must stand *Inside* their respective *Alliance Station*.

- a) During the *Qualification Matches* and the *Finals Round* of *Elimination Matches*, the blue *Alliance* Robots are set up on the *Playing Field* first, unless the red *Alliance* waives their right to set up on the *Playing Field* second.
- b) During the Round Robin Round of the Elimination Matches, the lower seeded Alliance Robots are set up on the Playing Field first, unless the higher seeded Alliance waives their right to set up on the Playing Field second. Alliance color doesn't change the ranking of a Team during the Elimination Matches.
- c) During Elimination Matches, four (4) Team Alliances (due to the addition of a Backup Robot) may only place three (3) Robots that are intended to compete in that Match. After the Robots are placed, the Alliance cannot swap in the Alliance's 4th Robot for a Robot already placed.

**<GS3> Autonomous Interference** - *Robots* may not *Interfere* with the opposing *Alliance's Scoring* attempts during the *Autonomous Period*. A *Major Penalty* will be assessed for each occurrence. Interactions at the centerline, including at centerline *Junctions* or *Transformer* starting positions, will not be considered *Interference*.

#### <GS5> Descoring

d) Robots may not *Descore Secured Transformers* from Junctions. Each violation of this rule results in a *Major Penalty* per *Scored Transformer*.

#### <GS6> Robot Control/Possession Limits for Scoring Elements -

f) Robots may Control or Possess a maximum of one (1) Transformer at one time. While a Robot Controls or Possesses a Transformer, that Robot may NOT Control or Possess any Cones or Beacons. Controlling or Possessing more than the allowed quantity of Transformers and/or Controlling or Possessing Transformers while possessing a Cone or Beacon is an immediate Minor Penalty for each Scoring Element above the limit plus an additional Minor Penalty per Scoring Element in excess of the limit for each 5-second interval that this situation continues.



NOTE: *Transformer* movement from the original starting location of one inch or less is inconsequential and therefore, does not violate rule <GS6>. Movement of the *Transformer* from the original starting location beyond this limit is subject to <GS6> f) rules. See <u>Q&A 204</u> regarding *Cone* stack movement, which is handled in a similar way.

#### <GS7> Junction and Terminal Constraints -

- a) A Cone or Transformer must be placed on a Junction with the large opening toward the Tile Floor to Score. A Cone or Transformer placed on a Junction in any other orientation is not Scored and may be removed by either Alliance.
- d) A Cone, <u>Transformer</u>, or Beacon may not be added to a Junction that has been Capped. These Cones, <u>Transformers</u>, or Beacons have zero (0) Score value, do not impact the Score of Cones below them (in the case of <u>Transformers</u>), and do not convey Ownership.
- e) A Transformer in a Terminal has zero (0) Score value and does not convey Ownership.
- f) A Cone, Transformer, or Beacon may not be added to a Junction that has a Secured Transformer. These Cones, Transformers, or Beacons have zero (0) Score value, do not impact the Score of Cones below them (in the case of Transformers), and do not convey Ownership.

#### <GS8> Junction and Terminal Defense -

a) A Robot may not impede or obstruct an opposing Alliance Robot from Scoring a Cone or Transformer on a Junction once the Cone or Transformer is In the Junction Area. Each violation of this rule results in an immediate Minor Penalty and additional Blocking Penalties per rule <G28>.

**<GS10> Cone/Transformer Constraint** – *Robots* may not place a *Transformer* or their own *Alliance's Cone/Beacon* on top of an unscored Transformer or opposing *Alliance's Cone/Beacon*. A *Minor Penalty* is assessed for each affected *Scoring Element*. *Cones* placed in violation of this rule may be removed without penalty. This rule does not apply to an upside-down *Cone* or *Transformer* on a *Low, Medium*, or *High Junction*.

**<GS11> Scoring while In a Substation** – A *Robot* must be *Completely Outside* of a *Substation* in order to *Score* a *Cone*, *Transformer*, or *Beacon*. Each violation of this rule results in a *Minor Penalty*.

<GS15> Transformer Constraint - Transformers may not be In any Alliance Specific Area, including the Terminal and Substations. An immediate Major Penalty plus an additional Minor Penalty for each 5-second interval that this situation continues will be assessed to that Area's Alliance. Intentional and/or repeated violations of this rule will escalate to Yellow Cards quickly.

NOTE: Additionally, <G28> will apply to any *Transformers* moved to be defensively trapped by an *Alliance* such that possession of a *Transformer* by the other *Alliance* is not possible.



# Scoring Summary

Scoring Achievement	Autonomous Points	Driver-Controlled Points	End Game Points
Robot Parked in Terminal	2		5
Robot Parked in Substation	2		
Robot Parked only on the Signal Zone that corresponds to the Signal image	10		
Robot Parked only on the Signal Zone that corresponds to the team supplied Signal Sleeve image	20		
		T	
Cone placed in a Terminal	1	1	
Cone Secured on Ground Junction	2	2	
Cone Secured on Low Junction	3	3	
Cone Secured on Medium Junction	4	4	
Cone Secured on High Junction	5	5	
Transformer Secured on Junction	3 per Alliance's Cone <b>Secured</b> below Transformer		
Junction Owned by Cone			3
Junction Owned by Beacon			10
Completed Circuit			40



# Tile Locations

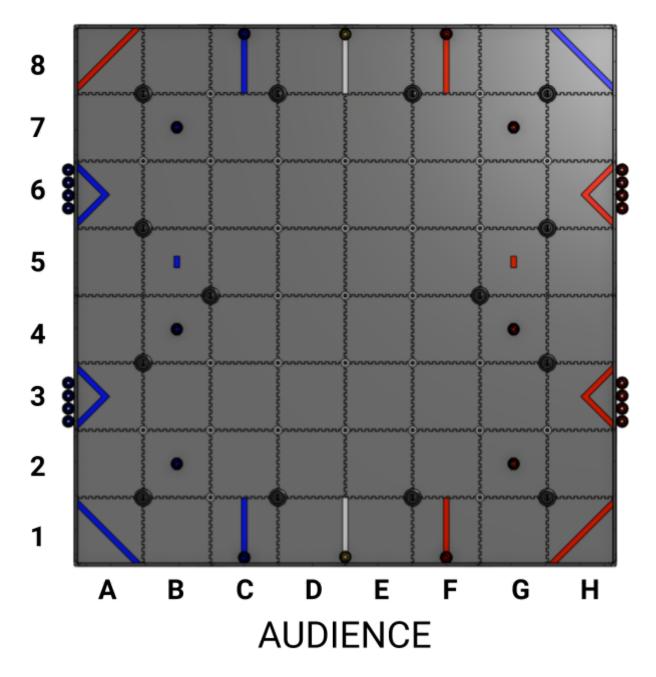
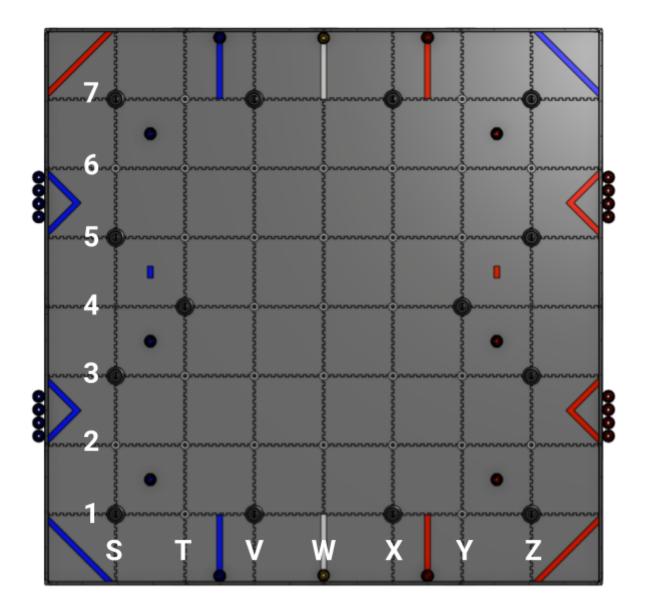


Diagram 6: Tile Locations



# Junction Locations



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Diagram 7: Junction Locations

